



**JAWAHARLAL NEHRU TECHNOLOGICAL UNIVERSITY: KAKINADA**  
**KAKINADA – 533 003, Andhra Pradesh, India**  
**R25 M.Tech ELECTRONICS & COMMUNICATION ENGINEERING**  
**DIGITAL ELECTRONICS & COMMUNICATION SYSTEMS**

**Vision and Mission of the University**

**VISION**

The University is primarily promoting quality of education in the areas of Science, Technology, Engineering and Mathematics (STEM) as four academic pillars of education, to excel in teaching, learning, research, consultancy and placements through innovative practices with global perspective.

**MISSION**

Design an Industry relevant curriculum from time to time with a Global perspective Promoting quality education by embracing ICT delivery mechanism with continuous pedagogy through e-learning mechanism Spread across for industry collaborations with a focus to pre-training and placements for technology transfer to society Establishing centers of excellence to promote research and innovations in multidisciplinary areas to bring in patent culture and consultancy practices International Collaborations for student outreach Facilitating international students to study in JNTUK to infuse cross culture learning practices.

Vision and Mission of the Institute

Vision and Mission of the Department



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### I Semester

S. No.	Course Name	Teaching Scheme			Credits
		L	T	P	
1.	Mathematical Foundation for Communication Engineering	3	1	0	4
2.	Digital System Design	3	1	0	4
3.	Wireless Communications & Networks	3	1	0	4
4.	<b>Elective I</b>	3	0	0	3
	1. Software Defined Radio				
	2. Optical Communication & Networks				
5.	<b>Elective II</b>	3	0	0	3
	1. FPGA and ASIC Design				
	2. System Design with RTOS & Embedded LINUX				
3. System Design Using Verilog					
6.	Digital System Design Laboratory	0	1	2	2
7.	Wireless Communications Laboratory	0	1	2	2
8.	Seminar – 1	0	0	2	1
9.	<b>Total Credits</b>	<b>15</b>	<b>5</b>	<b>6</b>	<b>23</b>

#### List of Professionals Elective Courses in I Semester (Electives-I&II)

S. No	Course Title
1	Software Defined Radio
2	Optical Communication & Networks
3	Radio and Navigational Aids
4	FPGA and ASIC Design
5	System Design with RTOS and Embedded LINUX
6	System Design Using Verilog



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## II Semester

S. No.	Name of the Subject	Teaching Scheme			Credits
		L	T	P	
1.	Information Theory and Coding	3	1	0	4
2.	IoT & its Communication Protocols	3	1	0	4
3.	Embedded System Design	3	1	0	4
4.	<b>Elective III</b>	3	0	0	3
	1. Design for Testability				
	2. MEMS				
5.	<b>Elective IV</b>	3	0	0	3
	1. Detection and Estimation Theory				
	2. EMI/ EMC				
	3. ARM Controllers and Embedded C				
6.	Internet of Things Lab	0	1	2	2
7.	Embedded System Design Lab	0	1	2	2
8.	Seminar – 2	0	0	2	1
9.	<b>Total Credits</b>	<b>15</b>	<b>5</b>	<b>6</b>	<b>23</b>

### List of Professionals Elective Courses in II Semester (Electives-III&IV)

S. No	Course Title
1	Design for Testability
2	MEMS
3	System on Chip Design
4	Detection and Estimation Theory
5	EMI/ EMC
6	ARM Controllers and Embedded C



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### III Semester

S. No.	Subject	Teaching Scheme			Credits
1	Research Methodology and IPR/ Swayam 12-week MOOC course – RM&IPR	3	0	0	3
2	Summer Internship / Industrial Training (8-10 weeks) *	-	-	-	3
3	Comprehensive Viva <sup>#</sup>	-	-	-	2
4	Dissertation Part – A <sup>\$</sup>	0	0	20	10
<b>Total</b>		<b>3</b>	<b>0</b>	<b>20</b>	<b>18</b>

\*Student attended during summer / year break and assessment will be done in 3<sup>rd</sup> sem.

# Comprehensive viva can be conducted courses completed up to second sem.

\$ Dissertation – Part A, internal assessment

### IV Semester

S. No.	Course Code	Subject	Teaching Scheme			Credits
			L	T	P	
1	Dissertation	Dissertation Part – B <sup>%</sup>	--	--	32	16
<b>Total Credits</b>			<b>--</b>	<b>--</b>	<b>32</b>	<b>16</b>

% External Assessment



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<b>I Semester</b>	<b>MATHEMATICAL FOUNDATION FOR COMMUNICATION ENGINEERING</b>	<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
		<b>3</b>	<b>1</b>	<b>0</b>	<b>4</b>

**COURSE OBJECTIVES:**

1. Understand foundational concepts of probability, sampling distributions, estimation, and hypothesis testing for statistical data analysis.
2. Develop analytical skills to handle random processes and Markov chains essential in stochastic modelling and simulation.
3. Acquire computational techniques for solving numerical problems involving interpolation, root finding, ODEs, and eigenvalue problems.
4. Explore mathematical optimization through multivariable calculus, constrained optimization techniques, and numerical methods.
5. Introduce wavelet transform concepts and their application to multi-resolution analysis in data and signal processing.

**UNIT- I: Probability and Statistics:**

Sampling distributions, Estimation of parameters (point estimation – unbiasedness & minimum variance, basics of interval estimation – confidence interval for mean), Testing of hypotheses (one and two sample tests for mean), Linear regression, Introduction to non-linear regression.

**UNIT - II: Stochastic process:**

Random processes, Random Walk, Markov process with special emphasis on Markov chain

**UNIT-III: Numerical Analysis:**

Introduction to Interpolation formulae [Bessel’s & Sterling’s], Roots of transcendental equations [Bisection, Regula-Falsi & Newton-Raphson] Solutions of simultaneous non-linear equations [Newton’s method], Numerical solution of Ordinary Differential equation [Modified Euler’s method, fourth order Runge-Kutta method], Matrix Eigen value and Eigen vector problems.

**UNIT- IV: Optimization Technique:**

Calculus of several variables, Implicit function theorem, Nature of singular points, Necessary and sufficient conditions for optimization, Constrained Optimization, Lagrange multipliers, Gradient method – steepest descent method.



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**UNIT- V: Wavelet Transform:**

Resolution problems, Multi-resolution analysis, Continuous & discrete wavelet transform

**TEXT BOOKS:**

1. A. Papoulis and S. Unnikrishnan Pillai, ``Probability, Random Variables and Stochastic Processes," Fourth Edition, McGraw Hill. (Indian Edition is available).
2. Gilbert Strang, " Linear Algebra and its applications", Thomson Learning Inc, 4th Edition.

**REFERENCE BOOKS:**

- 1.H.Stark and J. Woods, 'Probability and Random Processes with Applications to Signal Processing," Third Edition, Pearson Education. (Indian Edition is available).
- 2.Steven M. Kay, " Intuitive Probability and Random Process using MATLAB", Springer Publications.
- 3.Todd K Moon, Wynn C. Stirling" Mathematical Methods and Algorithms for Signal Processing, Prentice Hall.

**COURSE OUTCOMES**

By the end of this course, students will be able to:

1. Apply statistical methods including point estimation, confidence intervals, and hypothesis testing to real-world data scenarios.
2. Model and analyse stochastic systems using random processes, random walks, and Markov chains.
3. Solve engineering and scientific problems using numerical techniques such as Newton-Raphson, interpolation methods, and Runge-Kutta for differential equations.
4. Perform optimization tasks with or without constraints using gradient-based techniques and understand the role of Lagrange multipliers.
5. Use wavelet transforms to analyse signals and data with applications in compression and resolution enhancement.



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<b>I Semester</b>	<b>DIGITAL SYSTEM DESIGN</b>	<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
		<b>3</b>	<b>1</b>	<b>0</b>	<b>4</b>

**Course Objectives:**

1. Designing digital circuits, behavior and RTL modelling of digital circuits using Verilog HDL, verifying these Models and synthesizing RTL models to standard cell libraries and FPGAS.
2. Students gain practical experience by designing, modelling, implementing and verifying several digital
3. This course aims to provide students with the understanding of the different technologies related to HDLs, construct, compile and execute Verilog HDL programs using provided software tools

**UNIT - I:**

Introduction to Verilog HDL: Verilog as HDL, Levels of Design Description, Concurrency, Simulation and Synthesis, Function Verification, System Tasks, Programming Language Interface, Module, Simulation and Synthesis Tools Language Constructs and Conventions: Introduction, Keywords, Identifiers, White Space, Characters, Comments, Numbers, Strings, Logic Values, Strengths, Data Types, Scalars and Vectors, Parameters, Operators.

**UNIT - II:**

Gate Level Modelling: Introduction, AND Gate Primitive, Module Structure, Other Gate Primitives, Illustrative Examples, Tristate Gates, Array of Instances of Primitives, Design of Flip-Flops with Gate Primitives, Delay, Strengths and Construction Resolution, Net Types, Design of Basic Circuit.

**UNIT -III:**

Modelling at Dataflow Level: Introduction, Continuous Assignment Structure, Delays and Continuous Assignments, Assignment to Vector, Operators, Design at dataflow level, Parameter and constant usage in dataflow.

**UNIT - IV:**

Behavioral Modelling: Introduction, Operations and Assignments, Functional Bifurcation, 'Initial' Construct, Assignments with Delays, 'Wait Construct, Multiple Always Block, Designs at Behavioral Level



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**UNIT -V:**

Verilog Procedural and Control Constructs: Blocking and Non-Blocking Assignments, The 'Case' Statement, Simulation Flow, 'If an 'if-Else' Constructs, 'Assign- De-Assign' Constructs, 'Repeat' Construct, for loop, 'The Disable' Construct, 'While Loop', Forever Loop, Parallel Blocks, Force-Release, Construct, Event.

**TEXTBOOKS:**

1. T.R. Padmanabhan, B Bala Tripura Sundari, Design Through Verilog HDL, Wiley 2009.
2. Zainalabdien Navabi, Verilog Digital System Design, TMH, 2nd Edition.

**REFERENCE BOOKS:**

1. Fundamentals of Digital Logic with Verilog Design - Stephen Brown, Zvonkoc Vranesic, TMH, 2nd Edition.
2. Advanced Digital Logic Design using Verilog, State Machines & Synthesis for FPGA - Sunggu Lee, Cengage Learning, 2012.
3. Verilog HDL - Samir Palnitkar, 2nd Edition, Pearson Education, 2009.
4. Advanced Digital Design with Verilog HDL -Michel D. Ciletti, PHI,2009.

**COURSE OUTCOMES:**

Upon completion of the course students will be able to:

1. Understand the syntax, semantics, and simulation principles of Verilog HDL for digital system modelling.
2. Design and implement digital circuits using gate-level modelling and primitive components.
3. Develop dataflow-level models for digital systems using continuous assignments and operators.
4. Apply behavioural modelling techniques to describe complex digital systems using procedural constructs.
5. Utilize control constructs in Verilog to simulate, test, and verify digital designs effectively.



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<b>I Semester</b>	<b>WIRELESS COMMUNICATIONS &amp; NETWORKS</b>	<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
		<b>3</b>	<b>1</b>	<b>0</b>	<b>4</b>

**COURSE OBJECTIVES:**

1. To introduce the cellular system design concepts including frequency reuse, interference management, and handoff strategies.
2. To understand large-scale radio wave propagation models and their impact on wireless system performance.
3. To study small-scale fading, multipath propagation effects, and statistical models for channel behaviour.
4. To explore equalization and diversity techniques for improving signal quality in wireless environments.
5. To provide an overview of wireless networks and standards such as IEEE 802.11, IEEE 802.16, and wireless PANs.

**UNIT-I**

**The Cellular Concept-System Design Fundamentals:** Introduction, Frequency Reuse, Interference and system capacity – Co channel Interference and system capacity, Channel planning for Wireless Systems, Adjacent Channel interference, Power Control for Reducing interference, Improving Coverage & Capacity in Cellular Systems- Cell Splitting, Sectoring, Channel Assignment Strategies, Handoff Strategies- Prioritizing Handoffs, Practical Handoff Considerations, Trunking and Grade of Service

**UNIT-II**

**Mobile Radio Propagation: Large-Scale Path Loss:** Introduction to Radio Wave Propagation, Free Space Propagation Model, Relating Power to Electric Field, Basic Propagation Mechanisms, **Reflection:** Reflection from Dielectrics, Brewster Angle, Reflection from perfect conductors, Ground Reflection (Two-Ray) Model, **Diffraction:** Fresnel Zone Geometry, Knife-edge Diffraction Model, Multiple knife- edge Diffraction, Scattering, Outdoor Propagation Models- Longley-Ryce Model, Okumura Model, Hata Model, PCS Extension to Hata Model, Walfisch and Bertoni Model, Wideband PCS Microcell Model, Indoor Propagation Models- Partition losses (Same Floor), Partition losses between Floors, Log-distance path loss model, Ericsson Multiple Breakpoint Model, Attenuation Factor Model, Signal penetration into buildings, Ray Tracing and SiteSpecific Modeling.

**UNIT -III**

**Mobile Radio Propagation:** Small-Scale Fading and Multipath Small Scale Multipath propagation- Factors influencing small scale fading, Doppler shift, Impulse Response Model of a





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**COURSE OUTCOMES:**

Upon completion of the course students will be able to:

1. Understand cellular system design concepts including frequency reuse, interference management, and handoff strategies.
2. Analyse large-scale radio propagation models and apply them to outdoor and indoor wireless environments.
3. Evaluate small-scale fading effects and multipath propagation using statistical and empirical models.
4. Apply equalization and diversity techniques to improve wireless communication performance under varying channel conditions.
5. Demonstrate knowledge of wireless network standards, architectures, and protocols including IEEE 802.11 and 802.16.



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<b>I Semester</b>	<b>SOFTWARE DEFINED RADIO</b>	<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
		<b>3</b>	<b>0</b>	<b>0</b>	<b>3</b>

**COURSE OBJECTIVES:**

1. Introduce the evolution of radio communication systems and the fundamental concepts, architectures, and design principles of Software Defined Radio (SDR).
2. Understand the implementation challenges in RF front-end systems, including dynamic range, receiver topologies, and performance-affecting factors.
3. Explore digital signal generation techniques, particularly direct digital synthesis (DDS), and analyse related spurious signal behaviours.
4. Introduce multirate signal processing methods such as sample rate conversion, polyphase filters, and timing recovery in digital receivers.
5. Study analog-to-digital and digital-to-analog conversion techniques and methods for improving data converter performance in SDR systems.

**UNIT- I:**

Introduction to Software radio concepts: Introduction, need, characteristics, benefits and design principles of Software Radios. Traditional radio implemented in hardware (first generations of 2G cell phones), Software controlled radio (SCR), Software defined radio (SDR), Ideal software radio (ISR), Ultimate software radio (USR)

**UNIT- II:**

Radio frequency implementation issues: The purpose of RF Front-End, Dynamic range, RF Receiver Front-End Topologies, Enhanced Flexibility of the RF Chain with Software Radios, Importance of Components to Overall performance, Transmitter Architecture and their issues, Noise and Distortion in RF Chain.

**UNIT -III:**

Digital generation of signals: Introduction, Comparison of Direct Digital Synthesis with Analog Signal Synthesis, Approaches to Direct Digital Synthesis, Analysis of Spurious Signals, Spurious components due to Periodic Jitter.

**UNIT-IV:**

Multirate Signal Processing: Introduction, Sample Rate Conversion Principles, Polyphase Filters, Digital Filter Banks, Timing Recovery in Digital receivers Using Multirate Digital Filters.



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**UNIT- V:A/D & D/A Conversion:** Introduction, Parameters of Ideal Data Converters, Parameters of Practical data Converters, Techniques to improve Data Converter performance, JTRS.

**TEXT BOOKS:**

1. Jeffery H. Reed, “Software Radio, (A modern approach to radio engineering)”, PHI PTR, 2002
2. John J. Roupheal, “RF and Digital Signal Processing for Software Defined Radio” Elsevier, Newness Publications.

**REFERENCE BOOKS:**

1. C. Richard Johnson, Jr., and William A. Sethares, Telecommunication Breakdown, Prentice Hall, ISBN 0-13-143047-5, 2004
2. Software Defined Radio: Theory and Practice by John M. Reyland (Artech House, 2023)

**COURSE OUTCOMES:**

Upon completion of the course students will be able to:

1. Know the fundamentals of Software Radios, their evolution from traditional radios, and various levels including SCR, SDR, ISR, and USR.
2. Analyse RF front-end architectures, dynamic range requirements, and the role of RF Components in system performance for Software Radio implementation.
3. Explain and compare different signal generation techniques including direct digital synthesis, And analyse sources of spurious components and jitter effects.
4. Apply multi-rate signal processing techniques such as sample rate conversion, polyphase Filtering, and digital filter banks in software radio systems.
5. Evaluate the performance of A/D and D/A converters in practical systems, and describe Methods to improve conversion performance, including relevance to JTRS



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<b>I Semester</b>	<b>OPTICAL COMMUNICATION &amp; NETWORKS</b>	<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
		<b>3</b>	<b>0</b>	<b>0</b>	<b>3</b>

**COURSE OBJECTIVES:**

1. Introduce the fundamentals of optical fibre communication, including transmission link components, light propagation, and fibre structures.
2. Understand the principles and performance of optical sources and detectors used in optical communication systems.
3. Explain the structure and function of optical communication systems, including digital systems and modern high-speed links.
4. Familiarize students with components and technologies used in fibre optic networks and their architectures.
5. Explore coherent communication systems, detection techniques, and the role of demodulation and noise management in optical receivers.

**UNIT- I:**

Overview of optical fiber communications: Elements of an optical fiber transmission link. Optical Fibers: structures, wave guiding, Nature of light, Basic optical laws and definitions, optical fiber modes and configurations (Fiber types, Rays and modes, step index and graded index fibers) mode theory of circular waveguides. (Qualitative Treatment) Fabrication, cabling and installation: Fabrication, fiber optic cables, Installation- placing the cable.

**UNIT -II:**

**Optical sources:** LEDs, structures, quantum efficiency, modulation capability, Laser diodes: Laser diodes and threshold conditions, external quantum efficiency resonant frequencies, **Optical Detectors:** Physical principles of photodiodes (pin Photodiode, avalanche, photo diode)comparison of photo detectors, noise in detectors.

**UNIT -III:**

**Optical Communication Systems:** Block diagrams of optical communication systems, direct intensity modulation, digital communication systems, Laser semiconductor transmitter, Generations of optical fiber link, description of 8 Mb/s optical fiber communication link, description of 2.5 Gb/s optical fiber communication link.

**UNIT -IV:**

**Components of fiber optic Networks:** Overview of fiber optic networks, Trans receiver, semiconductors optical amplifiers, couplers/splicer’s, wavelength division multiplexers and



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demultiplexers, filters, isolators and optical switches. **Fiber Optic Networks:** Basic networks, SONET/SDIT, Broad cast and select WDM Networks, wavelength routed networks, optical CDMA Nonlinear effects on network performance.

**UNIT- V:**

**Coherent Systems:** **Coherent** receiver, Homodyne and heterodyne detection, noise in coherent receiver, polarization control, Homodyne receiver, Reusability and laser line-width, heterodyne receiver, synchronous, Asynchronous and self-synchronous demodulation, phase diversity receivers.

**TEXT BOOKS:**

1. Optical fiber communications – Gerd Keiser, 3 rd Ed. MGH.
2. Fiber Optic Communication Technology – Djafar K. Mynbaev and Lowell L. Scheiner,
3. Optoelectronic devices and systems – S.C. Gupta, PHI, 2005.

**REFERENCE BOOKS:**

- 1.Fiber Optics Communications – Harold Kolimbiris (Pearson Education Asia)
- 2.Optical Fiber Communications and its applications – S.C. Gupta (PHI) 2004.

**COURSE OUTCOMES:**

Upon completion of the course students will be able to :

1. Explain the fundamental principles of optical fiber communication including Wave guiding, fiber types, and mode theory of circular waveguides.
2. Compare and analyze various optical sources (LEDs, laser diodes) and detectors (PIN, APD) in terms of efficiency, modulation capability, and noise performance.
3. Design and interpret the block diagrams of optical communication systems and explain the working of digital systems including 8 Mb/s and 2.5 Gb/s optical links.
4. Evaluate different fiber optic network components such as transceivers, amplifiers, WDM Systems.
5. Demonstrate understanding of coherent optical systems including homodyne/heterodyne detection, polarization effects, and noise handling in coherent receivers.



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<b>I Semester</b>	<b>RADIO AND NAVIGATIONAL AIDS</b>	<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
		<b>3</b>	<b>0</b>	<b>0</b>	<b>3</b>

**COURSE OBJECTIVES:**

1. Understand the principles and configurations of radio positioning systems and factors affecting positioning accuracy.
2. Explore terrestrial radio navigation systems including LORAN, ILS, and indoor/urban positioning technologies.
3. Introduce fundamental navigation concepts such as position fixing, dead reckoning, and integrated navigation systems.
4. Study advanced satellite navigation techniques including Differential GNSS and carrier-phase positioning.
5. Examine inertial navigation systems and their equations, alignment methods, and error propagation models.

**UNIT- I: Principles of Radio Positioning:** Radio Positioning Configurations and Methods, Positioning Signals, User Equipment, Propagation, Error Sources, and Positioning Accuracy. Terrestrial Radio Navigation: Point-Source Systems, Loran, Instrument Landing System, Urban and Indoor Positioning, Relative Navigation, Tracking, Sonar Transponders.

**UNIT- II: Introduction To Navigation:** What Is Navigation, Position Fixing, Dead Reckoning, Inertial Navigation, Radio and Satellite Navigation, Terrestrial Radio Navigation, Satellite Navigation, Feature Matching, The Complete Navigation System.

**UNIT- III: Advanced Satellite Navigation:** Differential GNSS, Carrier-Phase Positioning and Attitude, Poor Signal-to-Noise Environments, Multipath Mitigation, Signal Monitoring, Semi Codeless Tracking.

**UNIT- IV: Inertial Navigation:** Inertial-Frame Navigation Equations, Earth-Frame Navigation Equations, Local-Navigation-Frame Navigation Equations, Navigation Equations Precision, Initialization and Alignment, INS Error Propagation, Platform INS, Horizontal-Plane Inertial Navigation.

**UNIT- V: Satellite Navigation & GNSS Systems:** Fundamentals: GPS, GLONASS, Galileo, Beidou, IRNSS, signal structure, measurement errors (ionospheric/tropospheric/multipath), Dilution of Precision (GDOP, PDOP), ephemeris, clock/correction errors, Differential GNSS, WAAS, integrity monitoring, carrier-phase techniques.

**TEXT BOOKS:**

1. G S RAO, Global Navigation Satellite Systems, McGraw-Hill Publications, New Delhi, 2010.



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2. Principles of GNSS, Inertial, and Multisensor Integrated Navigation Systems, Paul D. Groves Artech House, 2008 and 2013 Second Edition.
3. 2. B. Hofmann Wollenhof, H. Lichtenegger, and J. Collins, “GPS Theory and Practice”, Springer Wien, New York, 2000.

**REFERENCE BOOKS:**

1. Pratap Misra and Per Enge, “Global Positioning System Signals, Measurements, and Performance,” Ganga-Jamuna Press, Massachusetts, 2001.
2. Ahmed El-Rabbany, “Introduction to GPS,” Artech House, Boston, 2002.
3. Bradford W. Parkinson and James J. Spilker, “Global Positioning System: Theory and Applications,” Volume II, American Institute of Aeronautics and Astronautics, Inc., Washington, 1996.

**COURSE OUTCOMES:**

Upon completion of the course students will be able to:

- 1.Explain the principles, configurations, and error sources of terrestrial and radio positioning systems.
2. Apply various navigation methods to determine position and trajectory.
3. Analyse advanced satellite navigation techniques for accuracy enhancement.
4. Evaluate inertial navigation equations, alignment methods, and error propagation.
5. Integrate GNSS systems with error correction techniques for reliable navigation solutions.



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<b>I Semester</b>	<b>FPGA and ASIC DESIGN</b>	<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
		<b>3</b>	<b>0</b>	<b>0</b>	<b>3</b>

**COURSE OBJECTIVES:**

1. To introduce the evolution, design flow, and applications of FPGAs and PLDs.
2. To study various FPGA/CPLD programming technologies and commercially available devices.
3. To understand the internal architecture and building blocks of FPGAs/CPLDs and their impact on performance.
4. To explore routing architectures and strategies used in different FPGA types.
5. To analyse architectural elements and apply FPGA technology in real-world case studies.

**UNIT-I:**

INTRODUCTION TO FPGAs: Evolution of programmable devices, FPGA Design flow, Applications of FPGA.

DESIGN EXAMPLES USING PLDs: Design of Universal block, Memory, Floating point multiplier, Barrel shifter

**UNIT-II:**

FPGAs/CPLDs: Programming Technologies, Commercially available FPGAs, Xilinx’s Vertex and Spartan, Axtel’s FPGA, Altera’s FPGA/CPLD.

**UNIT-III:**

Building blocks of FPGAs/CPLDs: Configurable Logic block functionality, Routing structures, Input/output Block, Impact of logic block functionality on FPGA performance, Model for measuring delay.

**UNIT-IV:**

Routing Architectures: Routing terminology, general strategy for routing in FPGAs, routing for row – based FPGAs, introduction to segmented channel routing, routing for symmetrical FPGAs, example of routing in a symmetrical FPGA, general approach to routing in symmetrical FPGAs, independence from FPGA routing architectures, FPGA routing structures



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**UNIT-V:**

FPGA architectural assumptions, the logic block, the connection block, connection block topology, the switch block, switch block topology, architectural assumptions for the FPGA CASE STUDY – Applications using Kintex-7, Virtex-7, Artix-7.

**TEXT BOOKS:**

1. John V. Old Field, Richrad C. Dorf, Field Programmable Gate Arrays, Wiley, 2008.
2. VLSI Design: A Practical Guide for FPGA and ASIC Implementations by Vikram A. Chandrasetty (SpringerBriefs, 2011).

**REFERENCE BOOKS:**

1. Data sheets of Artix-7, Kintex-7, Virtex-7
2. Stephen D. Brown, Robert J. Francis, Jonathan Rose, Zvonko G. Vranesic, Field Programmable Gate Arrays, 2nd Edition, Springer, 1992.

**COURSE OUTCOMES:**

Upon completion of the course students will be able to :

1. Explain the evolution, design flow, and practical applications of FPGAs and PLDs.
2. Compare different FPGA/CPLD devices and their programming technologies.
3. Analyse the architecture of logic blocks, routing structures, and I/O blocks in FPGAs.
4. Apply routing techniques to various FPGA architectures for optimized performance.
5. Demonstrate FPGA design implementation using case studies on Kintex-7, Virtex-7, and Artix-7.



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<b>I Semester</b>	<b>SYSTEM DESIGN WITH RTOS &amp; EMBEDDED LINUX</b>	<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
		<b>3</b>	<b>0</b>	<b>0</b>	<b>3</b>

**COURSE OBJECTIVES:**

1. To introduce the key concepts of Real-Time Operating Systems and task management fundamentals.
2. To explore synchronization and communication mechanisms used in real-time systems.
3. To understand the role of exceptions, interrupts, and timer services in RTOS environments.
4. To provide hands-on experience with Linux kernels and shell scripting for embedded applications.
5. To analyse embedded Linux architecture and understand the process of application porting and driver integration.

**UNIT- I: Introduction to RTOS and Task Management**

Introduction to Real-Time Operating Systems (RTOS): Key characteristics, scheduler, kernel objects and services, system calls, static and dynamic libraries, cross tool chains, Task management: Defining tasks, task states, scheduling, task operations, synchronization, communication, concurrency.

**UNIT- II: Synchronization, Communication, and I/O Systems**

Semaphores: Operations, use cases, Message Queues: Types, operations, use cases (including pipes, event registers, signals, condition variables), I/O Subsystems: I/O concepts, subsystems, Synchronization and Communication: Resource synchronization methods, critical section, design patterns, priority inversion, common design problems (deadlocks, priority inversion).

**UNIT- III: Exceptions, Interrupts, and Timer Services**

Exceptions and Interrupts: Definitions, applications, spurious interrupts, Timer Services: Real-time clocks, system clocks, programmable interval timers, timer interrupt service routines.

**UNIT -IV: Linux Kernel and Shell Scripting**

Introduction to Linux Kernels: Linux basics, GNU utilities, distributions, access methods (CLI, graphical terminal emulators), Bash Shell Commands: Navigation, file handling, system monitoring, environment variables, user-defined variables, Shell Scripting: Script creation,



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control structures (if-else, loops, case commands), output redirection, practical examples, handling signals, background scripts, basic script functions, alternative shells (dash, zsh).

### **UNIT -V: Embedded Linux Architecture and Application Porting**

Embedded Linux Architecture: Kernel architecture, memory manager, scheduler, file system, I/O and networking subsystems, IPC, user space, startup sequence, Board Support Package: Embedded storage (MTD), embedded file system, embedded device drivers (communication kernel modules), Porting Applications: Real-time Linux, hard real-time programming, building and debugging (bootloaders, kernel, root file system, device tree).

#### **TEXT BOOKS:**

1. Qing Li, Caroline Yao (2020), “Real-Time Concepts for Embedded Systems”, CMP Books.
2. Chris Simmonds, “Mastering Embedded Linux Programming” - Second Edition, PACKT Publications Limited.

#### **REFERENCE BOOKS:**

1. Karim Yaghmour, “Building Embedded Linux Systems”, O’Reilly & Associates.
2. Mastering Embedded Linux Programming (3rd Edition) by Frank Vasquez & Chris Simmonds.

#### **COURSE OUTCOMES:**

After completing the course, students will be able to:

1. Describe RTOS features, kernel components, and manage task scheduling and synchronization.
2. Implement inter-task communication using semaphores, message queues, and handle I/O operations effectively.
3. Analyse the behaviour of exceptions, interrupts, and use timer services in real-time systems.
4. Use Linux shell commands and scripts to perform system-level operations and automation tasks.
5. Demonstrate understanding of embedded Linux internals and port applications with BSP and device drivers.



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<b>I Semester</b>	<b>SYSTEMS DESIGN USING VERILOG</b>	<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
		<b>3</b>	<b>0</b>	<b>0</b>	<b>3</b>

**COURSE OBJECTIVES:**

1. Designing digital circuits, behaviour and RTL modelling of digital circuits using verilog HDL, verifying these Models and synthesizing RTL models to standard cell libraries and FPGAS.
2. Students gain practical experience by designing, modelling, implementing and verifying several digital
3. This course aims to provide students with the understanding of the different technologies related to HDLs, construct, compile and execute Verilog HDL programs using provided software tools.

**UNIT - I: Introduction to Verilog HDL:** Verilog as HDL, Levels of Design Description, Concurrency, Simulation and Synthesis, Function Verification, System Tasks, Programming Language Interface, Module, Simulation and Synthesis Tools Language Constructs and Conventions: Introduction, Keywords, Identifiers, White Space, Characters, Comments, Numbers, Strings, Logic Values, Strengths, Data Types, Scalars and Vectors, Parameters, Operators.

**UNIT - II: Gate Level Modelling:** Introduction, AND Gate Primitive, Module Structure, Other Gate Primitives, Illustrative Examples, Tristate Gates, Array of Instances of Primitives, Design of Flip-Flops with Gate Primitives, Delay, Strengths and Construction Resolution, Net Types, Design of Basic Circuit.

**UNIT -III: Modelling at Dataflow Level:** Introduction, Continuous Assignment Structure, Delays and Continuous Assignments, Assignment to Vector, Operators, Design at dataflow level, Parameter and constant usage in dataflow.

**UNIT - IV: Behavioural Modelling:** Introduction, Operations and Assignments, Functional Bifurcation, 'Initial' Construct, Assignments with Delays, 'Wait Construct, Multiple Always Block, Designs at Behavioural Level

**UNIT -V: Verilog Procedural and Control Constructs:** Blocking and Non-Blocking Assignments, The 'Case' Statement, Simulation Flow, 'If an 'if-Else' Constructs, 'Assign- De-Assign' Constructs, 'Repeat' Construct, for loop, 'The Disable' Construct, 'While Loop', Forever Loop, Parallel Blocks, Force-Release, Construct, Event.



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**TEXT BOOKS:**

1. T.R. Padmanabhan, B Bala Tripura Sundari, Design Through Verilog HDL, Wiley 2009.
2. Zainalabdien Navabi, Verilog Digital System Design, TMH, 2nd Edition.

**REFERENCE BOOKS:**

1. Fundamentals of Digital Logic with Verilog Design - Stephen Brown, Zvonko Vranesic, TMH, 2<sup>nd</sup> Edition.
2. Advanced Digital Logic Design using Verilog, State Machines & Synthesis for FPGA - Sunggu Lee, Cengage Learning, 2012.
3. Verilog HDL - Samir Palnitkar, 2nd Edition, Pearson Education, 2009.
4. Advanced Digital Design with Verilog HDL - Michel D. Ciletti, PHI, 2009.

**COURSE OUTCOMES:**

Upon completion of the course students will be able to:

1. Describe Verilog hardware description, languages(HDL).
2. Design digital circuits.
3. Write Behavioural models of digital circuits.
4. Write Register Transfer Level (RTL) models of Digital Circuits.
5. Verify Behavioural and RTL models.



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<b>I Semester</b>	<b>DIGITAL SYSTEM DESIGN LABORATORY</b>	<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
		<b>0</b>	<b>1</b>	<b>2</b>	<b>2</b>

**COURSE OBJECTIVES:**

1. To introduce algorithms for efficient combinational and sequential logic design such as CAMP-I, CAMP-II, and Kohavi.
2. To familiarize students with programmable logic array (PLA) design, minimization, and folding techniques.
3. To develop skills in the design and implementation of ROM and control logic units.
4. To enable practical experience in digital system implementation using FPGA platforms.
5. To understand and experiment with error detection/correction and finite state machine design concepts.

**Systems Design experiments:**

- The students are required to design the logic to perform the following experiments using necessary Industry standard simulator to verify the logical /functional operation, perform the analysis with appropriate synthesizer and to verify the implemented logic with different hardware modules/kits (CPLD/FPGA kits).
- Consider the suitable switching function and data to implement the required logic if required.

A student must do at least 10 Experiments.

**List of Experiments:**

1. Determination of EPCs using CAMP-I Algorithm.
2. Determination of SPCs using CAMP-I Algorithm.
3. Determination of SCs using CAMP-II Algorithm.
4. PLA minimization algorithm (IISc algorithm)
5. PLA folding algorithm(COMPACT algorithm)
6. ROM design.
7. Control unit and data processor logic design
8. Digital system design using FPGA.
9. Kohavi algorithm.
10. Hamming experiments.



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**COURSE OUTCOMES:**

After successful completion of the course, students will be able to:

1. Apply CAMP-I and CAMP-II algorithms to determine essential, secondary, and spurious prime implicants.
2. Implement PLA minimization and folding using IISc and COMPACT algorithms respectively.
3. Design **and** realize ROM-based systems and control/data path logic circuits.
4. Develop digital systems using FPGA tools and platforms for real-time applications.
5. Perform logic minimization using Kohavi's algorithm and **analyze** error-correcting codes through Hamming experiments.



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<b>I Semester</b>	<b>WIRELESS COMMUNICATIONS LABORATORY</b>	<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
		<b>0</b>	<b>1</b>	<b>2</b>	<b>2</b>

**COURSE OBJECTIVES:**

1. To understand and analyse digital communication techniques including error detection and correction.
2. To provide hands-on experience in spread spectrum systems, convolutional coding, and decoding.
3. To apply signal processing techniques using transforms, filtering, and DSP hardware platforms.
4. To explore image processing operations and study their effects on digital images.
5. To study and experiment with optical fiber communication, mobile phone trainers, CDMA, and ISDN systems.

**PART A: List of Experiments :( Minimum of Ten Experiments must be performed)**

- 1.Measurement of Bit Error Rate using Binary Data
- 2.Verification of minimum distance in Hamming code
- 3.Determination of output of Convolution Encoder for a given sequence
- 4.Determination of output of Convolution Decoder for a given sequence
- 5.Efficiency of DS Spread- Spectrum Technique
- 6.Simulation of Frequency Hopping (FH) system
- 7.Effect of Sampling and Quantization of Digital Image
- 8.Verification of Various Transforms (FT / DCT/ Walsh / Hadamard) on a given Image  
(Finding Transform and Inverse Transform)
- 9.Point, Line and Edge detection techniques using derivative operators.
- 10.Implementation of FIR filter using DSP Trainer Kit (C-Code/ Assembly code)
- 11.Implementation of IIR filter using DSP Trainer Kit (C-Code/ Assembly code)
- 12.Determination of Losses in Optical Fiber
- 13.Observing the Waveforms at various test points of a mobile phone using Mobile Phone Trainer
- 14.Study of Direct Sequence Spread Spectrum Modulation & Demodulation using CDMA-DSSBER Trainer
- 15.Study of ISDN Training System with Protocol Analyzer
- 16.Characteristics of LASER Diode.



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**PART B: Equipment required for Laboratory Software:**

1. MATLAB along with Simulink Licensed simulation software tool with communication and Signal

processing Toolbox.

2. Computer Systems with required specifications

**Hardware:**

1. Hardware kits for verification of BER

2. Hardware kits of Convolution encoders, Hamming encoders.

3. Frequency spectrum

4. Mobile Phone Trainer

5. DSP Trainer Kit

6. CDMA-DSS-BER Trainer

7. ISDN Training System with Protocol Analyzer

8. Optical fiber Transmitter and receiver kit along with different lengths of cables

**COURSE OUTCOMES:**

After successful completion of the course, students will be able to:

1. Measure bit error rates and verify error correction capabilities using Hamming codes.
2. Simulate and analyze convolutional encoder/decoder systems and spread spectrum techniques.
3. Implement and evaluate digital signal processing algorithms (FIR/IIR filters) on DSP trainer kits.
4. Apply transforms (FT, DCT, Walsh, Hadamard) and perform edge/line detection in digital images.
5. Experiment with optical fiber characteristics, mobile phone trainer systems, and CDMA/ISDN technologies.



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<b>I Semester</b>	<b>SEMINAR – I</b>	<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
		<b>0</b>	<b>0</b>	<b>2</b>	<b>1</b>



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<b>II Semester</b>	<b>INFORMATION THEORY AND CODING</b>	<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
		<b>3</b>	<b>1</b>	<b>0</b>	<b>4</b>

**COURSE OBJECTIVES:**

1. Introduce core concepts of information theory including entropy and mutual information.
2. Teach lossless source coding algorithms like Huffman, Arithmetic, and LZW.
3. Explain channel capacity and its evaluation for various communication channels.
4. Explore the fundamentals of video and speech coding techniques.
5. Provide knowledge of error control coding for reliable data transmission.

**UNIT-I: Introduction**

Information Source, Symbols, and Entropy, Mutual information, information Measures for Continuous Random Variable, Joint and Conditional Entropy, Relative Entropy, Applications Based on information Theoretic Approach.

**UNIT-II: Source coding**

Source Coding Theorem, Kraft inequality, Shannon-Fano Codes, Huffman Codes, Run Length Code, Arithmetic Codes, Lempel-Ziv-Welch Algorithm, Universal Source Codes, Prefix Codes, Variable Length Codes, Uniquely Decodable Codes, instantaneous Codes, Shannon’s Theorem, Shannon Fano Encoding Algorithm, Shannon’s Noiseless Coding Theorem, Shannon’s Noisy Coding Theorem.

**UNIT-III: Communication channel**

Channel and its Capacity, Continuous and Gaussian Channels, Discrete Memory-Less Channels, Symmetric Channel, Binary Erasure Channel, Estimation of Channel Capacity, Noiseless Channel, Channel Efficiency, Shannon’s Theorem on Channel Capacity, Mimo Channels, Channel Capacity with Feedback.

**UNIT-IV: Video and speech coding**

Video Coding Basics, Quantization, Symbol Encoding, Intraframe Coding, Predictive Coding, Transform Coding, Subband Coding, Vector Quantization, Interframe Coding, Motion Compensated Coding, Image Compression, Jpeg, LZ78 Compression, Dictionary Based Compression, Statistical Modelling, Speech Coding, Psycho-Acoustic Modelling, Time Frequency Mapping Quantization, Variable Length Coding, Multichannel Correlation and Irrelevancy, Long Term Correlation, Pre-Echo Control, Bit Allocation.



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**UNIT-V: Error control coding**

Overview of Field, Group, Galois Field, Types of Codes, Hamming Weight, Minimum Distance Based Codes, Error Detection and Error Correction Theorems, Maximum Likelihood Decoder, Map Decoder, Linear Block Codes and Their Properties, Equivalent Codes, Generator Matrix and Parity Check Matrix, Systematic Codes, Cyclic Codes, Convolution Codes and Viterbi Decoding Algorithm, Iterative Decoding, Turbo Codes and Low Density-Parity-Check Codes, Asymptotic Equipartition Property, Bch Codes, Generator Polynomials, Decoding of Bch Codes, Reed Solomon Codes, Trellis Codes, Space Time Coding.

**TEXT BOOKS:**

1. T.M. Cover and J.A. Thomas, Elements of Information Theory, John Wiley & Sons.
2. Todd K. Moon, Error Correction coding, John Wiley, 2005.

**REFERENCE BOOKS:**

1. Shu lin/ Daniel J.Costello Jr., Error Control Coding, Prentice Hall series in computer applications in electrical engineering series (2/e) 2005.
2. Ranjan Bose, Information Theory, coding and cryptography (2/e), McGraw Hill

**COURSE OUTCOMES:**

1. Understand and compute entropy, mutual information, and related measures.
2. Apply and analyse source coding algorithms for efficient data compression.
3. Evaluate channel capacity and efficiency in communication systems.
4. Implement and compare video/speech coding and multimedia compression techniques.
5. Design and analyse error control codes for error detection and correction



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<b>II Semester</b>	<b>IOT AND ITS COMMUNICATION PROTOCOLS</b>	<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
		<b>3</b>	<b>1</b>	<b>0</b>	<b>4</b>

**COURSE OBJECTIVES:**

1. Introduce the core architecture and technologies of IoT, including devices, gateways, networking, data management, and services.
2. Familiarize students with IoT reference architectures, views, and the design constraints encountered in real-world implementations.
3. Understand data link and network layer protocols that support communication in IoT systems, including both traditional and IoT-specific protocols.
4. Explore transport and session layer protocols essential for reliable and efficient data transfer in IoT communication models.
5. Explain service layer and security protocols used in IoT systems, emphasizing interoperability and secure communication.

**UNIT-I**

**Introduction:** IoT architecture outline, standards - IoT Technology Fundamentals- Devices and gateways, Local and wide areanetworking, Data management, Business processes in IoT, Everything as a Service(XaaS), M2M and IoT Analytics

**UNIT-II**

**IoT Reference Architecture:** Introduction, Functional View, Information View, Deployment and Operational View, Other Relevant architectural views. Real-World Design Constraints- Introduction, Technical Designconstraints

**UNIT-III**

**IoT Data Link Layer & Network Layer Protocols:** PHY/MAC Layer (3GPP MTC, IEEE 802.11, IEEE 802.15), Wireless HART, Z-Wave, Bluetooth Low Energy, Zigbee Smart Energy, DASH7 - Network Layer-IPv4,IPv6, 6LoWPAN, 6TiSCH,ND, DHCP, ICMP, RPL, CORPL, CARP

**UNIT -IV**

**IoT Transport & Session Layer Protocols:** Transport Layer (TCP, MPTCP, UDP, DCCP, SCTP)-(TLS, DTLS) – Session Layer-HTTP, CoAP, XMPP, AMQP, MQTT

**UNIT -V**

**IoT Service Layer Protocols & Security Protocols:** Service Layer -oneM2M, ETSI M2M, OMA, BBF – Security in IoT Protocols – MAC802.15.4 , 6LoWPAN, RPL, Application Layer.



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**TEXT BOOKS:**

1 Daniel Minoli, “Building the Internet of Things with IPv6 and MIPv6: The Evolving World of M2M Communications”, ISBN: 978-1-118-47347-4, Willy Publications ,2016.

2 Jan Holler, Vlasios Tsiatsis, Catherine Mulligan, Stefan Aves and, Stamatis Karnouskos, David Boyle, “From Machine-to-Machine to the Internet of Things: Introduction to a New Age of Intelligence”, 1st Edition, Academic Press, 2015.

**REFERENCE BOOKS**

1. Bernd Scholz-Reiter, Florian Michahelles, “Architecting the Internet of Things”, ISBN 978-3-642 19156-5 e-ISBN 978-3-642-19157-2, Springer, 2016.

2. N. Ida, Sensors, Actuators and Their Interfaces, Scitech Publishers, 2014.

**COURSE OUTCOMES:**

- 1.Understand the fundamental components and architecture of IoT systems
- 2.Interpret and apply various IoT reference architectural views
- 3.Analyse data link and network layer protocols used in IoT communication
- 4.Evaluate transport and session layer protocols for their suitability in IoT applications
- 5.Assess IoT service layer and security protocols to ensure interoperability and secure communication



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<b>II Semester</b>	<b>EMBEDDED SYSTEM DESIGN</b>	<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
		<b>3</b>	<b>1</b>	<b>0</b>	<b>4</b>

**COURSE OBJECTIVES:**

1. To introduce the fundamentals, classification, and characteristics of embedded systems.
2. To explore the core components of embedded systems including processors, memory, and interfaces.
3. To understand embedded firmware components and design approaches.
4. To study ARM processor architecture, instruction sets, and programming model.
5. To provide practical exposure to Raspberry Pi programming, communication protocols, and sensor interfacing.

**UNIT -I**

**Introduction to Embedded Systems:** Definition of Embedded System, Embedded Systems Vs General Computing Systems, History of Embedded Systems, Classification, Major Application Areas, Purpose of Embedded Systems, Characteristics and Quality Attributes of Embedded Systems.

**UNIT- II**

**Typical Embedded System:** Core of the Embedded System: General Purpose and Domain Specific Processors, ASICs, PLDs, Commercial Off-The-Shelf Components (COTS), Memory: ROM, RAM, Memory according to the type of Interface, Memory Shadowing, Memory selection for Embedded Systems, Sensors and Actuators, Communication Interface: Onboard and External Communication Interfaces.

**UNIT -III**

**Embedded Firmware:** Reset Circuit, Brown-out Protection Circuit, Oscillator Unit, Real Time Clock, Watchdog Timer, Embedded Firmware Design Approaches and Development Languages.

**UNIT -IV**

**ARM:** ARM design philosophy, data flow model and core architecture, registers, program status register, instruction pipeline, interrupts and vector table, operating modes and ARM processor families. Instruction Sets: Data processing instructions, addressing modes, branch, load, store instructions, PSR instructions, and conditional instructions.

**UNIT -V**

**Raspberry Pi:** Raspberry Pi board and its processor, Programming the Raspberry Pi using Python, Communication facilities on Raspberry Pi (I2C, SPI, UART), Interfacing of sensors and actuators.



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**TEXT BOOKS:**

1. Introduction to Embedded Systems - Shibu K.V, Mc Graw Hill.
2. A. N. Sloss, D. Symes, and C. Wright, "ARM System Developer's Guide: Designing and Optimizing System Software", Elsevier, 2008.
3. S. Monk, "Programming the Raspberry Pi" McGraw-Hill Education, 2013.

**REFERENCE BOOKS:**

1. Steve Furber, "ARM system-on-chip architecture", Addison Wesley, 2000.
2. Embedded Systems - Raj Kamal, TMH.
3. Embedded System Design - Frank Vahid, Tony Givargis, John Wiley.

**COURSE OUTCOMES:**

After successful completion of the course, students will be able to:

1. Describe the structure, classification, and purpose of embedded systems and their quality attributes.
2. Analyse embedded system components such as processors, memory types, sensors, actuators, and interfaces.
3. Explain embedded firmware building blocks and apply suitable design approaches.
4. Demonstrate knowledge of ARM architecture and instruction sets relevant to embedded programming.
5. Develop simple embedded applications using Raspberry Pi and interface sensors and communication peripherals.



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<b>II Semester</b>	<b>DESIGN FOR TESTABILITY</b>	<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
		<b>3</b>	<b>0</b>	<b>0</b>	<b>3</b>

**COURSE OBJECTIVES:**

1. To introduce the fundamental concepts, types, and philosophies of VLSI testing.
2. To familiarise fault models and apply logic/fault simulation techniques for test evaluation.
3. To study testability measures and design-for-test (DFT) techniques including scan design.
4. To explore Built-In Self-Test (BIST) strategies and their application in digital systems.
5. To learn the boundary scan architecture and standards used in board-level testing.

**UNIT-I: Introduction to Testing**

Testing Philosophy, Role of Testing, Digital and Analog VLSI Testing, VLSI Technology Trends affecting Testing, Types of Testing, Fault Modelling: Defects, Errors and Faults, Functional Versus Structural Testing, Levels of Fault Models, Single Stuck-at Fault.

**UNIT-II: Logic and Fault Simulation**

Simulation for Design Verification and Test Evaluation, Modelling Circuits for Simulation, Algorithms for True-value Simulation, Algorithms for Fault Simulation.

**UNIT -III: Testability Measures**

SCOAP Controllability and Observability, High Level Testability Measures, Digital DFT and Scan Design: Ad-Hoc DFT Methods, Scan Design, Partial-Scan Design, Variations of Scan.

**UNIT-IV: Built-In Self-Test**

The Economic Case for BIST, Random Logic BIST: Definitions, BIST Process, Pattern Generation, Response Compaction, Built-In Logic Block Observers, Test-Per-Clock, Test-Per-Scan BIST Systems, Circular Self-Test Path System, Memory BIST, Delay Fault BIST.

**UNIT-V: Boundary Scan Standard**

Motivation, System Configuration with Boundary Scan: TAP Controller and Port, Boundary Scan Test Instructions, Pin Constraints of the Standard, Boundary Scan Description Language: BSDL Description Components, Pin Descriptions.



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**TEXT BOOKS:**

1. Essentials of Electronic Testing for Digital, Memory and Mixed Signal VLSI Circuits - M.L. Bushnell, V. D. Agrawal, Kluwer Academic Publishers.
2. VLSI Test Principles and Architectures: Design for Testability” – L.-T. Wang, C.-W. Wu, X. Wen

**REFERENCE BOOKS:**

1. Digital Systems and Testable Design - M. Abramovici, M.A.Breuer and A.D Friedman, Jaico Publishing House.
2. Digital Circuits Testing and Testability - P.K. Lala, Academic Press.

**COURSE OUTCOMES:**

1. Explain the role of testing in VLSI systems and differentiate between fault models and testing types.
2. Apply simulation algorithms for design verification and fault analysis in digital circuits.
3. Evaluate testability using measures like SCOAP and design scan-based test structures.
4. Design and implement BIST strategies for logic and memory testing.
5. Demonstrate understanding of boundary scan standards and describe systems using BSDL.



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<b>II Semester</b>	<b>MEMS</b>	<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
		<b>3</b>	<b>0</b>	<b>0</b>	<b>3</b>

**COURSE OBJECTIVES:**

1. To introduce the fundamentals, materials, and applications of MEMS and smart systems.
2. To explore various types of micro-sensors, actuators, and smart material-based systems.
3. To study micro-fabrication techniques including deposition, lithography, and micromachining.
4. To understand the mechanical modelling of microstructures such as beams, bars, and multilayer elements.
5. To apply numerical analysis techniques like Finite Element Method (FEM) for modelling MEMS structures.

**UNIT-I**

**Introduction to MEMS:** Microsystems versus MEMS, Micro fabrication, Smart Materials, Structures and Systems, Integrated Microsystems, Applications of Smart Materials and Microsystems

**UNIT-II**

**Micro Sensors, Actuators, Systems and Smart Materials:** Silicon Capacitive Accelerometer, Piezo-resistive Pressure Sensor, Conductometric Gas Sensor, An Electrostatic Comb-Drive, A Magnetic Micro relay, Portable Blood Analyzer, Piezoelectric Inkjet Print Head, Micro-mirror Array for Video Projection Smart Materials and Systems

**UNIT -III**

**Micro Fabrication Technique:** Silicon as a Material for Micromachining, Thin-Film Deposition, Lithography, Etching, Silicon Micromachining Specialized Materials for Microsystems, Advanced Processes for Micro fabrication

**UNIT-IV**

**Modeling Of Solids in Microsystems:** The Simplest Deformable Element: A Bar, Transversely Deformable Element: A beam, Energy Methods for Elastic Bodies, Heterogeneous Layered Beams, Bimorph Effect, Residual Stresses and Stress Gradients, Poisson Effect and the Anticlastic Curvature of Beams, Torsion of Beams and Shear Stresses, Dealing with Large Displacements, In-Plane Stresses

**UNIT-V**

**Finite Element Method:** Need for Numerical Methods for Solution of Equations - Variational Principles, Finite Element Method, Finite Element Model for Structures with Piezoelectric Sensors and Actuators, Analysis of a Piezoelectric Bimorph Cantilever Beam



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**TEXT BOOKS:**

1. Fundamentals of Microfabrication — *Marc J. Madou* (CRC Press, 1997/2002).
2. An Introduction to Microelectromechanical Systems Engineering — N. Maluf (Artech House, 1999).

**REFERENCE BOOKS:**

1. Micro and Smart Systems by G.K. Ananthasuresh, K.J. Vinoy, S.Gopalakrishnan, K.N.Bhat, V.K.Aatre: Wiley, India (2016).
2. Smart Material Systems and MEMS: Design and Development Methodologies: Vijay K., 2017  
The MEMS Handbook: Edited by Mohamed Gad-el-Hak, University of Notre Dame, CRC Press LLC, 2015

**COURSE OUTCOMES:**

After successful completion of the course, students will be able to:

1. Describe the basic concepts of MEMS, microfabrication, and smart materials.
2. Identify and explain the working principles of micro-sensors, actuators, and MEMS devices.
3. Demonstrate knowledge of various micro-fabrication processes used in MEMS manufacturing.
4. Analyse mechanical behaviour of MEMS structures using energy methods and elasticity concepts.
5. Apply FEM techniques for modelling and simulation of MEMS devices with piezoelectric elements.



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<b>II Semester</b>	<b>SYSTEM ON CHIP DESIGN</b>	<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
		<b>3</b>	<b>0</b>	<b>0</b>	<b>3</b>

**COURSE OBJECTIVES:**

1. To introduce the fundamentals of SoC architecture, components, and design methodologies.
2. To understand hardware-software co-design concepts including partitioning, scheduling, and hardware acceleration.
3. To explore virtual prototyping, high-level synthesis, and system-level design methodologies.
4. To examine SoC interconnection structures and protocols like AMBA AXI and Network-on-Chip (NoC).
5. To analyse performance and power at the system level using simulation platforms and case studies.

**UNIT-I:** SoC Design Approach: Basics of Chips and SoC ICs, SoC Design: SoC CPU/IP Cores, Co-processor, Cache, DRAM Controller, SoC Synthesis, Static Timing Analysis (STA), Design for Testability, Verification, Physical Design.

**UNIT-II:**

Hardware-Software Co-Synthesis: Partitioning, Cycle Time, Die Area and Cost, Power, Area-Time-Power Trade-offs and Chip Reliability, Real-Time Scheduling, Hardware Acceleration.

**UNIT-III:** Virtual Prototyping and High-Level Synthesis (HLS): Mapping High-Level Language Applications to Hardware, Transaction-Level Modeling and Electronic System-Level Languages, Hardware Accelerators, Media Instructions, Coprocessors, System-Level Design Methodology, High-Level Synthesis (C-to-RTL), Hardware Synthesis and Architecture Techniques, Source-Level Optimizations.

**UNIT-IV:** SoC Interconnection Structures: Bus-Based Interconnection, Bus Protocols: AMBA AXI Bus, AXI4-Stream, IBM Core Connect, Avalon. Interconnection Structures, Network on Chip (NoC) Interconnection and NoC Systems, IP Interfacing.

**UNIT-V:** Performance/Power Analysis of SoCs: System-Level Modeling and Integration, Simulation Platform for Performance Analysis of SoC/MPSoC, Use Cases and Examples.



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**TEXT BOOKS:**

1. Veena Chakravarthi, A Practical Approach to VLSI System on Chip (SoC) Design – A Comprehensive Guide, Springer, 2020
2. S. Pasricha and N. Dutt, On-Chip Communication Architectures: System on Chip Interconnect, Morgan Kaufmann–Elsevier Publishers, 2008

**REFERENCE BOOKS:**

1. Keating, M., The Simple Art of SoC Design, Springer, 2011.
2. "Embedded System Design: A Unified Hardware/Software Approach" Authors: Frank Vahid and Tony Givargis, Publisher: Wiley

**COURSE OUTCOMES:**

At the end of the course, students will be able to:

1. Understand and estimate key design metrics and requirements including area, latency, throughput, energy, and power.
2. Implement both hardware and software solutions, formulate hardware/software trade-offs, and perform hardware/software co-design.
3. Analyse issues in system-on-chip design associated with interconnection structures, performance, and power consumption.
4. Use System C programming and high-level synthesis (HLS) for design and modelling.
5. Design and optimize a modern System-on-a-Chip.



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<b>II Semester</b>	<b>DETECTION AND ESTIMATION THEORY</b>	<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
		<b>3</b>	<b>0</b>	<b>0</b>	<b>3</b>

**COURSE OBJECTIVES:**

1. To introduce fundamental concepts of random processes including Markov models, point processes, and Gaussian processes.
2. To develop understanding of detection theory using Bayesian and Neyman-Pearson approaches for signal classification under uncertainty.
3. To explore MMSE estimation techniques such as Wiener and Kalman filters for linear and nonlinear systems.
4. To provide knowledge of statistical inference including hypothesis testing, distribution estimation, and regression analysis.
5. To enable parameter estimation of random processes using model-free and model-based approaches with spectral analysis tools.

**UNIT –I**

Random Processes: Discrete Linear Models, Markov Sequences and Processes, Point Processes, and Gaussian Processes.

**UNIT –II**

Detection Theory: Basic Detection Problem, Maximum A posteriori Decision Rule, Minimum Probability of Error Classifier, Bayes Decision Rule, Multiple-Class Problem (Bayes)- minimum probability error with and without equal a priori probabilities, Neyman-Pearson Classifier, General Calculation of Probability of Error, General Gaussian Problem, Composite Hypotheses.

**UNIT –III**

Linear Minimum Mean-Square Error Filtering: Linear Minimum Mean Squared Error Estimators; Nonlinear Minimum Mean Squared Error Estimators. Innovations, Digital Wiener Filters with Stored Data, Real-time Digital Wiener Filters, Kalman Filters.

**UNIT –IV**

Statistics: Measurements, Nonparametric Estimators of Probability Distribution and Density Functions, Point Estimators of Parameters, Measures of the Quality of Estimators, Introduction to Interval Estimates, Distribution of Estimators, Tests of Hypotheses, Simple Linear Regression, Multiple Linear Regression.

**UNIT –V**

Estimating the Parameters of Random Processes from Data: Tests for Stationarity and Ergodicity, Model-free Estimation, Model-based Estimation of Autocorrelation Functions, Power Spectral Density Functions.



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**TEXT BOOKS:**

1. Steven M. Kay, “Fundamentals of Statistical signal processing, volume 1: Estimation theory”. Prentice Hall 2011.
2. Steven M. Kay, “Fundamentals of Statistical signal processing, volume 2: Detection theory”. Prentice Hall 2011.

**REFERENCE BOOKS:**

1. Harry L. Van Trees, “Detection, Estimation, and Modulation Theory, Part I,” John Wiley & Sons, Inc. 2011
2. A. Papoulis and S. Unnikrishna Pillai, “Probability, Random Variables and stochastic processes, 4e”. The McGraw-Hill 2010

**COURSE OUTCOMES:**

1. Demonstrate understanding of random processes, including discrete linear models, Markov processes, point processes, and Gaussian processes relevant to signal processing.
2. Apply detection theory to solve problems using MAP, Bayes, and Neyman-Pearson decision rules for both binary and multiple hypothesis testing.
3. Develop and analyze linear and nonlinear minimum mean square error (MMSE) estimators, and design digital Wiener and Kalman filters for signal estimation.
4. Estimate and interpret statistical parameters and distributions using point estimation, nonparametric methods, interval estimates, hypothesis testing, and linear regression models.
5. Evaluate stationarity and ergodicity of random processes and perform both model-free and model-based estimation of autocorrelation and power spectral density functions from data.



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<b>II Semester</b>	<b>EMI/ EMC</b>	<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
		<b>3</b>	<b>0</b>	<b>0</b>	<b>3</b>

**COURSE OBJECTIVES:**

1. To introduce enough knowledge regarding the Electromagnetic interference/ Electromagnetic compatibility, Its practical experiences and concerns, and various sources both the natural and nuclear sources of EMI.
2. To know the practical experiences due to EMI such as mains power supply, switches and relays etc and Analyse EM Propagation and Crosstalk
3. To know various methods of the measurements radiated and conducted interference in open area test sites and in chambers.
4. To Learn about the various methods of minimizing the EMI.
5. To know the National/International EMC Standards.

**UNIT -I: Introduction, Natural and Nuclear Sources of EMI / EMC:**

Electromagnetic environment, History, Concepts, Practical experiences and concerns, frequency spectrum conservations, An overview of EMI / EMC, Natural and Nuclear sources of EMI.

**UNIT -II: EMI from Apparatus, Circuits and Open Area Test Sites:**

Electromagnetic emissions, Noise from relays and switches, non-linearities in circuits, passive intermodulation, Cross talk in transmission lines, Transients in power supply lines, Electromagnetic interference (EMI), Open area test sites and measurements.

**UNIT -III: Radiated and Conducted Interference Measurements and ESD:**

Anechoic chamber, TEM cell, GH TEM Cell, Characterization of conduction currents / voltages, Conducted EM noise on power lines, Conducted EMI from equipment, Immunity to conducted EMI detectors and measurements, ESD, Electrical fast transients / bursts, Electrical surges.

**UNIT -IV: Grounding, Shielding, Bonding and EMI filters:**

Principles and types of grounding, Shielding and bonding, Characterization of filters, Power lines filter design.

**UNIT -V: Cables, Connectors, Components and EMC Standards:**

EMI suppression cables, EMC connectors, EMC Gas kets, Isolation Transformers, optoisolators, National / International EMC standards.

**TEXT BOOKS:**

1. Engineering Electromagnetic Compatibility - Dr. V.P. Kodali, IEEE Publication, Printed in India by S. Chand & Co. Ltd., New Delhi, 2000.
2. Electromagnetic Interference and Compatibility IMPACT series, IIT – Delhi, Modules 1-9



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**REFERENCE BOOKS:**

1. Introduction to Electromagnetic Compatibility - Ny, John Wiley, 1992, by C.R. Pal.

**COURSE OUTCOMES:**

At the end of this course the student can able to:

1. Understand the electromagnetic environment the definitions of EMI and EMC, history of EMI some examples of practical experiences due to EMI such as mains power supply, switches and relays etc.
2. Understand the celestial electromagnetic noise the occurrence of lightning discharge and their effects, the charge accumulation and discharge in an electrostatic discharge, model ESD wave form, the various cases of nuclear explosion and the transients.
3. Understand the methods to measure RE and RS in the open are test sites.
4. Understand the measurement facilities and procedures using anechoic chamber, TEM cell, reverberating chamber GTEM cell.
5. Apply grounding, shielding, bonding techniques, and design EMI filters for interference mitigation.



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<b>II Semester</b>	<b>ARM CONTROLLERS AND EMBEDDED C</b>	<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
		<b>3</b>	<b>0</b>	<b>0</b>	<b>3</b>

**COURSE OBJECTIVES:**

1. To introduce ARM processor architecture, instruction sets, and efficient programming techniques.
2. To explore exception handling, memory hierarchy, and management units in ARM systems.
3. To develop embedded system applications using ARM Cortex-M microcontrollers.
4. To implement peripheral interfacing techniques including UART, ADC/DAC, and GPIO.
5. To understand communication protocols like I<sup>2</sup>C and SPI through practical case studies.

**UNIT- I: ARM Processor Fundamentals:** ARM Design Philosophy, Registers, CPSR, Pipeline, Exceptions, Interrupts and Vector Table, Core Extensions.

**Introduction to the ARM Instruction Set:** Data Processing Instructions, Branch Instructions, Load Store Instructions, Software Interrupt Instruction, PSR Instructions.

**Introduction to the Thumb Instruction Set:** Thumb Register Usage, Branch Instructions, Data Processing Instructions, Load-Store Instructions, Stack instructions, Software Interrupt Instruction.

**Efficient C Programming:** Basic C Data Types, C Looping Structures, Register Allocation, Function Calls, Structure Arrangement.

**Writing and Optimizing ARM Assembly Code:** Writing Assembly Code, Profiling and Cycle Counting, Instruction Scheduling, Register Allocation, Conditional Execution, Looping Constructs.

**UNIT -II: Exception and Interrupt Handling:** Exception Handling, Interrupts, Interrupt Handling Schemes

**Caches:** The Memory Hierarchy and Cache Memory, Cache Architecture, Cache Policy, Flushing and Cleaning Cache Memory.

**Memory Protection Units:** Protected Regions, Initializing the MPU, Caches and Write Buffer.

**Memory Management Units:** Moving from an MPU to an MMU, How Virtual Memory Works, Details of the ARM MMU, Page Tables, Translation Lookaside Buffer, Domains And Memory Access Permission, The Fast Context Switch Extension

**UNIT- III: Introduction:** Definition of Embedded Systems, Real life examples of embedded systems, Basics of Developing for Embedded Systems.

**ARM Instruction set Architecture:** ARM Cortex-M Organization, Arithmetic, Logical and Shift instructions, Data Movement Instructions, Branch instructions, Program Status register,



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Bitwise logic operations, Sign and Zero extension, Data Comparison, Memory addressing, Branch and conditional execution, Control structures, Subroutines, 64-bit data processing.

**GPIO:** GPIO Input Modes, GPIO Output Modes, Memory-mapped I/O, Push button, Programming exercises on GPIO and Push-button

**General-purpose Timers:** Clock Configuration, Timer Organization, and Counting Modes, Timer Update Events, PWM Registers, Configuration and initialization of PWM block, Programming exercises on the selection of clock source, Timer's concept, and PWM

**UNIT-IV: UART:** UART Block, UART Registers, UART baud rate calculation, Configuration and initialization of UART.

**ADC/DAC:** ADC & DAC registers, pin configuration, ADC modes, Configuring ADC and DAC module, Programming exercises on ADC and DAC

**Interfacing:** Keypad, LCD, and Seven segment display interfacing with ARM Cortex-M3 Microcontroller

**UNIT-V:**

**Inter-Integrated Circuit (I<sup>2</sup>C):** I<sup>2</sup>C operating modes, Configuration of I<sup>2</sup>C, Interface a sensor using I<sup>2</sup>C protocol. **Serial Peripheral Interface (SPI):** SPI Modes, Master operation, Slave operation, Configuration of SPI. **Case Study:** Smart Home-Smart Door Locks and Interface a temperature sensor with an I<sup>2</sup>C Module to measure the room temperature.

**TEXT BOOKS:**

1. A.Sloss, D.Symes, C.Wright, "ARM system Developers Guide: Designing and Optimizing System Software", Morgan Kaufmann publishers, 2012.
2. Dr.Yifeng Zhu "Embedded Systems with ARM Cortex-M Microcontrollers in Assembly and C" Third edition, 2018

**REFERENCE BOOKS:**

1. Steve Furber, "ARM System on Chip Architecture", 2<sup>nd</sup> ed., Addison Wesley Professional, 2000.
2. Valvano, J, "Embedded microcomputer systems: real time interfacing", 3<sup>rd</sup> Edition, Cengage Learning, 2011.
3. Frank Vahid, TonyGivargis, "Embedded System Design", J Wiley India, 2005.
4. Ariel Lutenberg, Pablo Gomez, Eric Pernia "A Beginner's Guide to Designing Embedded System Applications on Arm Cortex-M Microcontrollers"
5. Qing Li, Caroline Yao "Real-time concepts for Embedded Systems" CMP books.



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**COURSE OUTCOMES:**

1. Demonstrate proficiency in ARM instruction sets and assembly code optimization.
2. Configure and manage exceptions, interrupts, and memory systems in ARM-based designs
3. Develop embedded applications using GPIO, timers, and control structures.
4. Interface and program peripherals such as UART, ADC/DAC, and display modules.
5. Apply I<sup>2</sup>C and SPI protocols in real-world scenarios like smart home systems



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<b>II Semester</b>	<b>INTERNET OF THINGS LAB</b>	<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
		<b>0</b>	<b>1</b>	<b>2</b>	<b>2</b>

**COURSE OBJECTIVES:**

1. To introduce students to the fundamentals of IoT architecture and physical layer components.
2. To familiarize students with sensors, actuators, transducers, microcontrollers, and microprocessors used in IoT.
3. To provide hands-on experience with Arduino, Scratch programming, S4A tool, and Arduino IDE.
4. To develop practical skills using Tinker cad simulations and real-time Arduino-based interfaces.
5. To enable interfacing of digital and analog sensors and actuators with Arduino for real-time applications.

**List of Experiments:**

1. Introduction to IoT, IoT Architecture, introduction to Physical layer
2. Introduction to sensors, actuators, and transducers. Introduction to microcontrollers and microprocessors
3. Introduction to Arduino. Introduction to Scratch programming, S4A tool, and Arduino IDE.
4. Introduction to Tinker cad and some practical examples
5. Working with analog, digital inputs & outputs
6. Interfacing Arduino with Embedded sensors and Actuators
7. Interfacing Arduino with additional sensors
8. Working on Displays and interfacing with Arduino
9. Arduino & LCD Based Projects
10. Arduino interfacing with Keypad and its operation
11. Creating the app (app designing using MIT) and controlling your hardware with your app.
12. Introduction to NodeMCU and basic tasks
13. Introduction to Cloud, some IoT Cloud Platforms publishing sensor data to a cloud using Thing speak
14. Controlling your sensor data using Thing speak and MIT APP Inventor
15. Email notifications, app alerts using Blynk cloud
16. Home Automation Using Blynk app



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**COURSE OUTCOMES:**

At the end of the Course the student shall be able to

1. Analyze the concepts of IoT along with its applications.
2. Design a prototype using Arduino Uno.
3. Analyze different types of sensors, actuators and communication Protocols.
4. Execute a prototype of Home Automation using Blynk app.
5. Design an IoT application to interact with cloud.



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<b>II Semester</b>	<b>EMBEDDED SYSTEM DESIGN LAB</b>	<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
		<b>0</b>	<b>1</b>	<b>2</b>	<b>2</b>

**COURSE OBJECTIVES:**

1. To introduce students to GPIO configuration and control in embedded systems.
2. To develop skills in serial communication between microcontrollers and PCs using UART.
3. To understand timer and counter functionalities for time delays and interrupts.
4. To provide experience with LCD interfacing and real-time message display.
5. To implement analog-to-digital conversion and PWM signal generation for control applications.

**Experiments using ARM Cortex-M Microcontroller: (NUCLEO board -F429ZI):**

- 1.Program to configure and control General Purpose Input / Output (GPIO) port pins.
- 2.Program to demonstrate Serial communication. Transmission from Kit and reception from PC using Serial Port on IDE environment use debug terminal to trace the program.
- 3.Program to demonstrate Time delay program using built in Timer / Counter feature on IDE environment.
- 4.Program to demonstrate a simple interrupt handler and setting up a timer.
- 5.Program to Displaying a message in a 2-line x 16 Characters LCD display and verify the result in debug terminal.
- 6.Program to demonstrate ADC interfacing.
- 7.Generation of PWM Signal with the objective of introducing the practical application of timers and fundamental principles of control theory.
- 8.To integrate a micro-SD card with the computing system for the purpose of storing event logs conveniently on the SD card.
- 9.To establish a connection between the two computing systems using Bluetooth Low Energy (BLE), with the objective of monitoring pertinent information from one system and facilitating gate control through the other system.
- 10.To enhance the smart home system by enabling it to host a web page through Wi-Fi connectivity, thereby allowing users to access information using a smartphone or PC.

**COURSE OUTCOMES:**

After successful completion of this lab course, students will be able to:

1. Configure and control GPIO ports and interface with external devices.
2. Implement UART-based serial communication and use debug terminals for testing.
3. Apply timers and counters for generating delays and handling interrupts in real-time systems.





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<b>II Semester</b>	<b>SEMINAR – II</b>	<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
		<b>0</b>	<b>0</b>	<b>2</b>	<b>1</b>



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<b>III Semester</b>	<b>RESEARCH METHODOLOGY AND IPR</b>	<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
		<b>3</b>	<b>0</b>	<b>0</b>	<b>3</b>

**COURSE OBJECTIVES:**

1. To introduce the fundamentals of research methodology, including research design and problem formulation.
2. To develop skills for effective literature review, data collection, analysis, and technical writing.
3. To enhance understanding of ethical issues and plagiarism in research.
4. To provide an overview of intellectual property rights, including patents, copyrights, trademarks, and trade secrets.
5. To create awareness about the process of filing IPR and its role in innovation, entrepreneurship, and academic research.

**UNIT-I:** Meaning of research problem, Sources of research problem, Criteria Characteristics of a good research problem, Errors in selecting a research problem, Scope and objectives of research problem. Approaches of investigation of solutions for research problem, data collection, analysis, interpretation, Necessary instrumentations

**UNIT-II:** Effective literature studies approaches, analysis Plagiarism, Research ethics, Effective technical writing, how to write report, Paper Developing a Research Proposal, Format of research proposal, a presentation and assessment by a review committee

**UNIT-III:** Nature of Intellectual Property: Patents, Designs, Trademarks and Copyright. Process of Patenting and Development: technological research, innovation, patenting, development. International Scenario: International cooperation on Intellectual Property. Procedure for grants of patents, Patenting under PCT.

**UNIT-IV:** Patent Rights: Scope of Patent Rights, Licensing and transfer of technology, Patent information and databases, Geographical Indications.

**UNIT-V:**

New Developments in IPR: Administration of Patent System. New developments in IPR, IPR of Biological Systems, Computer Software etc. Traditional knowledge Case Studies, IPR and IITs.

**TEXT BOOKS:**

1. Stuart Melville and Wayne Goddard, “Research methodology: an introduction for science & engineering students”.
2. Wayne Goddard and Stuart Melville, “Research Methodology: An Introduction”



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**DIGITAL ELECTRONICS & COMMUNICATION SYSTEMS**

**REFERENCES :**

1. Ranjit Kumar, 2nd Edition, “Research Methodology: A Step by Step Guide for beginners”
2. Halbert, “Resisting Intellectual Property”, Taylor & Francis Ltd,2007.
3. Mayall, “Industrial Design”, McGraw Hill,1992.
4. Niebel, “Product Design”, McGraw Hill,1974.
5. Asimov, “Introduction to Design”, Prentice Hall,1962.
6. Robert P. Merges, Peter S. Menell, Mark A. Lemley, “Intellectual Property in New TechnologicalAge”,2016.
- 7.T. Ramappa, “Intellectual Property Rights Under WTO”, S. Chand,2008

**COURSE OUTCOMES:**

At the end of this course, students will be able to

1. Understand research problem formulation.
2. Analyze research related information and Follow research ethics
3. Understand that today’s world is controlled by Computer, Information Technology, but tomorrow world will be ruled by ideas, concept, and creativity.
4. Understanding that when IPR would take such important place in growth of individuals & nation, it is needless to emphasis the need of information about Intellectual Property Right to be promoted among students in general & engineering in particular.
5. Understand that IPR protection provides an incentive to inventors for further research work and investment in R & D, which leads to creation of new and better products, and in turn brings about, economic growth and social benefits.





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<b>III Semester</b>	<b>COMPREHENSIVE VIVA#</b>	<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
		<b>0</b>	<b>0</b>	<b>0</b>	<b>2</b>



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<b>III Semester</b>	<b>DISSERTATION PART– A<sup>s</sup></b>	<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
		<b>0</b>	<b>0</b>	<b>20</b>	<b>10</b>



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<b>IV Semester</b>	<b>DISSERTATION PART- B%</b>	<b>L</b>	<b>T</b>	<b>P</b>	<b>C</b>
		<b>0</b>	<b>0</b>	<b>32</b>	<b>16</b>